Microprocessor Final Report

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Abstract:

A breathalyzer is a device that measures and displays the breath alcohol content (BrAC) of a person. It samples the air that it detects for ethanol, and some models use this to change the voltage output of a printed circuit board (PCB). A simple circuit was constructed to fit the constraints of the analog-digital converter (ADC) on the STM32F401RE microcontroller unit (MCU). The ADC reading is then processed on the MCU and transformed into the appropriate two-digit reading, which is 5 bits long. The MCU then sends this reading over SPI to the MAX10 FPGA on the Arrow MAX1000 PCB. The FPGA then takes this information and time multiplexes rows of LEDs to display the two digits on an 8-by-8 LED matrix. Calibration was done by taking various measurements with a store-bought breathalyzer. This was successfully implemented, and the system as a whole behaves as desired.

Introduction:

The final project of E155 directed students to use the principles taught in the class to design and build a complex system that implements novel hardware not previously used in the labs. A volatile organic compound (VOC) sensor's resistance changes based on the level of a compound it detects in the air around it. Certain ones can detect ethanol, which appears in the breath of a person who has consumed alcohol. Alcohol consumption can have serious consequences, especially when it comes to the operation of motor vehicles, which is why laws are in place based on the blood alcohol (BAC) of a person. Because of this, using a sensor to display the BAC of the user is highly valuable, as it can prevent a person from participating in dangerous activities or getting arrested. This was the motivation behind this project.

The block diagram shown below in Figure 1 shows an overview of the entire breathalyzer system.

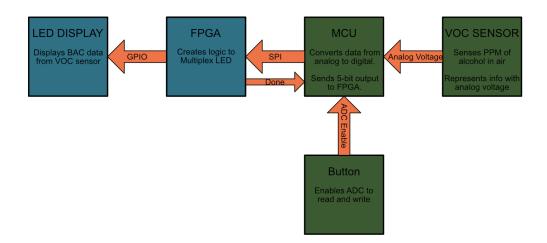


Figure 1: Overall System Block Diagram

As seen in the block diagram, the MCU is taking in the input from the VOC sensor and sending converted data to the FPGA, which runs the 8 by 8 LED matrix. The other human input is a button that tells the MCU to take a measurement.

VOC Sensor and Circuit:

The VOC sensor used in this project is the MiCS 5524. This sensor is capable of detecting concentrations of up to 500 ppm of ethanol. The PCB that includes the sensor takes in a 5V and GND input from the MCU, and outputs a voltage that increases with as the concentration of alcohol it detects increases. However, due to reasons that will be explained later, the ADC can only read values between 0V and 3.3V, while the output of the PCB can reach 5V. To combat this, the ADC will read the voltage in between two identical resistors linking the output to ground, which makes the maximum readable voltage 2.5V, which the ADC is able to read.

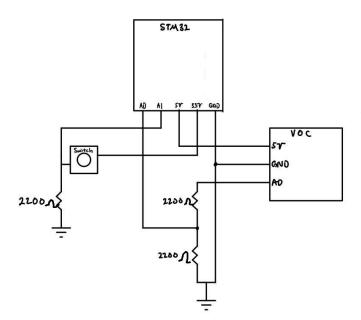


Figure 2: VOC to MCU Connections

MCU ADC Usage:

The ADC on the MCU converts the analog voltage output of the VOC sensor circuit, which is connected to pin A0 on the MCU, into a 12 bit number, which is the highest resolution possible for this unit. The 12 bit number is output by the ADC according to the Equation 1, with analog voltage on pin A0 as an input:

$$OUT = IN \cdot ((V_{REF+} - V_{REF-})/2^{N})$$
 (1)

In this case, V_{REF+} is 3.3V, V_{REF-} is 0V, and N is 12, meaning that the ADC outputs a number from 0 to 4095.

The ADC has the option of aligning the number to the left or the right, and the right-aligned option was chosen because when storing the number in a variable, the code will convert the binary number to a number in decimal format. Right shifting allows this number to be read correctly, rather than being shifted and multiplied by a certain amount.

The ADC has 16 channels to sample the voltages of, and any sequence of channels can be sampled in any order. For this project, the only channel used was ADC_IN0, which connected to pin A0 when it was set as an analog pin. The ADC also has single conversion mode, continuous conversion mode, and scan mode. Single conversion mode was used for this project, as it was desired to take only one measurement at the push of a button, shown in Figure 2. There are also sequence registers that keep track of the amount of channels to sample and what order to do so in. These registers were set to 1 channel and ADC_IN0, respectively.

Transformation to BAC on MCU:

As stated in a previous section, the maximum ethanol concentration that the BAC can detect is 500ppm, which roughly translates to 0.1974% BAC. To represent this fact, the code on the MCU converts the ADC reading to a 5 bit binary unsigned integer between 0 and 19. A calibration curve was found by blowing into a store-bought breathalyzer and then reading the voltage on pin A0 with an oscilloscope. Equation 2 below shows the polynomial curve found to be the calibration curve, where x is the BAC in hundreths of a percentage point.

$$Voltage = 44.7352 \cdot x^2 - .5527 \cdot x + .207 (2)$$

The code takes into account what ADC outputs these voltages translate to, and properly maps them onto a binary unsigned integer between 0 and 19. This value is then stored onto a variable, which is now ready to be sent to the FPGA via SPI.

MCU SPI Communication:

The MCU communicates the 5-bit value calculated during the prior step to the FPGA. This value is placed into the SPI data register, which is set to 8 bits and most significant bit first, and is shifted out on the rising edge of the SPI clock. The MCU acts as the SPI master while the FPGA acts as the client, except that it does not send data back to the MCU. The clock speed is set by a prescaler in the RCC and the SPI prescaler. The prescaler of the RCC was 16, and the SPI prescaler was set to 256. This caused the SPI clock to have a frequency of 10253 Hz. This low frequency was chosen so that the FPGA was able to sample the incoming bits while also running slowly enough that digits on the LED matrix did not bleed together. Figure 3 below shows the connections between the FPGA and MCU.

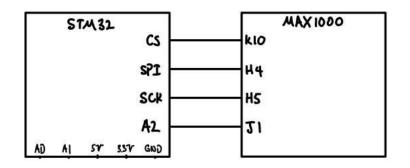


Figure 3: MCU to FPGA SPI Connections

MCU Algorithm:

After initializing and enabling the clock and necessary peripherals, the code enters a while loop and then waits for a button press. Once the button is pressed, pin A1 is driven high which tells the ADC to take a single measurement of the voltage output of the VOC circuit. It stores this measurement in a variable, and then puts that value through the voltage to BAC conversion mentioned in a previous section. A timer on the MCU activates to count to 1 second, which prevents any debouncing issues from causing the ADC to read multiple measurements with one button press. The MCU then sends the 5-bit value over SPI, which ends up being an 8-bit value with 3 leading zeroes. The MCU then waits for the FPGA to respond with a high signal that goes to pin A2, indicating that it has received and implemented the 5-bit number in the way that will be described later in the FPGA section of the report.

FPGA SPI Reception:

The FPGA hardware was programmed to be able to receive the 8-bit serially transmitted data from the MCU by causing it to act as a shift register. Essentially, 8 parallel bits were designated, the 5 least significant of which would be the input to the FPGA LED Multiplexing system that will be described in the next section of the report. Using a flop, at every positive edge of the SCK input from the microcontroller, the value on the H4 pin at that time will be shifted in as the least significant bit. This happens 8 times per transmission, so that the 5-bit number will be used as the input to the multiplexing module. Using a counter, the FPGA's clock runs at 20507 Hertz, twice as fast as SCK. This is to ensure that each of the shifts are detected and that, as mentioned previously, the digits on the LED matrix don't bleed together.

FPGA LED Multiplexing:

The FPGA takes in the 5 least significant bits of the SPI data from the MCU, decodes the data to a percentage (0.00, 0.01, 0.02 . . . 0.20) and displays the data on an LED matrix via multiplexing. A seven state FSM is used to determine which row of the LED is turned on for multiplexing. Combinational logic is used to determine which LEDs to assert based on which row is powered and which number needs to be displayed. Transistors are used to provide power to each row of the LED matrix.

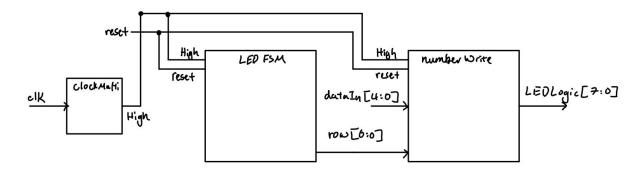


Figure 4: FPGA Block Diagram Without SPI

Results:

The system works as intended. The voltages read on the oscilloscope match the ADC and BAC readings that are read in the debugger in VS Code. The system reacts to the presence of alcohol in many forms. It reacts to the presence of vodka on one's breath, the presence of mouthwash containing alcohol on one's breath, and even the presence of mouthwash on a cotton ball held closely to the sensor. This means that the breathalyzer can be demonstrated in a professional setting while also adhering to COVID regulations, which is what was desired from the system when it was first thought of.

References:

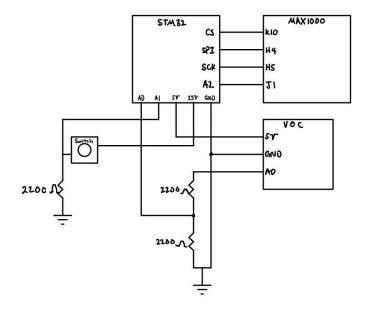
lady ada. Adafruit. https://learn.adafruit.com/adafruit-mics5524-gas-sensor-breakout July 2016

http://www.mecinca.net/ALCOHOLIMETROS_Alcosim/BAC%20BrAC%20conversion%20table[1]

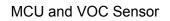
https://senseair.com/knowledge/information-and-education/gases/c-h-oh-ethanol/

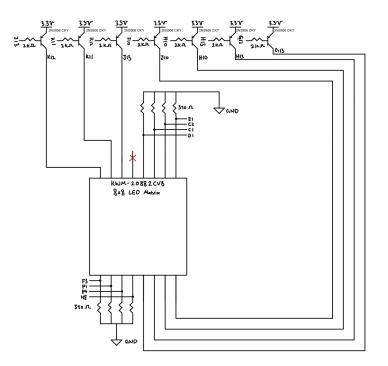
Bill of Materials:

Material	Quantity	Cost	Total Cost
STM32F401RE MCU	1	0	0
MAX1000	1	0	0
MiCS 5524 Sensor + PCB + Shipping	1	\$62.00 \$62.00	\$62.00
2N3906 Transistor	7	0	0
2200 Ohm Resistor	3	0	0
390 Ohm Resistor	8	0	0
Push Button	1	0 0	0
8x8 LED Matrix	1	0	0
2000 Ohm Resistor	7	0	0
2700 Ohm Resistor	4	0	0
Total			\$62.00



Appendix A: Breadboard Schematics





FPGA and LED

Appendix B: MCU Code

```
final_project.c
```

```
#include "STM32F401RE GPIO.h"
#include "STM32F401RE FLASH.h"
#include "STM32F401RE RCC.h"
#include "STM32F401RE ADC.h"
#include "STM32F401RE SPI.h"
#include "STM32F401RE TIM.h"
#include <string.h> // for strstr()
#include <stdint.h> // for integer types (i.e., uint32 t)
#include <stdio.h> // for sprintf()
uint8 t ADCto5bits(uint16 t adc){
 uint8 t a;
 if (adc > (.207*4096/(3.3*2))){
    if(adc > (.209*4096/(3.3*2)))
      if(adc > (.2138*4096/(3.3*2))){
        if(adc > (.2307*4096/(3.3*2))){
          if (adc > (.2565*4096/(3.3*2))){
            if(adc > (.2912*4096/(3.3*2))){
              if(adc > (.3349*4096/(3.3*2))){
                if(adc > (.3875*4096/(3.3*2))){
                  if(adc > (.4491*4096/(3.3*2))){
                    if(adc > (.5196*4096/(3.3*2)))
                      if(adc > (.5991*4096/(3.3*2))){
                        if(adc > (.6875*4096/(3.3*2)))
                          if(adc > (.7849*4096/(3.3*2)))
                            if(adc > (.8912*4096/(3.3*2)))
                              if(adc > (1.0064*4096/(3.3*2))){
                                if(adc > (1.1306*4096/(3.3*2)))
                                  if(adc > (1.2638*4096/(3.3*2))){
                                    if(adc > (1.4059*4096/(3.3*2)))
                                      if(adc > (1.5569*4096/(3.3*2)))
                                        a = 19;}
                                      else {a = 18;}
                                    }
                                    else {a = 17;}
                                  }
                                  else {a = 16;}
                                }
                                else {a = 15;}
                              }
                              else {a = 14;}
                            }
                            else {a = 13;}
```

```
}
                          else {a = 12;}
                        }
                        else {a = 11;}
                      }
                      else {a = 10;}
                    }
                    else {a = 9;}
                  }
                  else {a = 8;}
                }
                else {a = 7;}
              }
              else {a = 6;}
            }
            else {a = 5;}
          }
          else {a = 4;}
        }
       else {a = 3;}
     }
      else {a = 2;}
    }
   else {a = 1;}
  }
 else {a = 0;}
 return a;
}
int main(void) {
 // Configure the flash and then set clock to 84 MHz from PLL
 configureFlash();
 configureClock();
 RCC->APB2ENR.ADC1EN = 1;
 // Turn on GPIOA
 RCC->AHB1ENR.GPIOAEN = 1;
 //Enable timer
 RCC->CFGR.HPRE = 0b0001;
 RCC->APB2ENR.TIM11EN = 1;
 // Set PAO as an input for the ADC, another pin as input for reading and
another for signaling ready
 pinMode(GPIOA, 0, GPIO ANALOG);
 pinMode(GPIOA, 1, GPIO INPUT);
 pinMode(GPIOA, 4, GPIO_INPUT);
```

```
durationTimer();
// Set MISO, MOSI, SCK, and CE
spiInit(0b111, 0, 0);
// Initialize the ADC
ADCinit();
//digitalWrite(GPIOB, 6, 1);
uint16 t b;
//b = measure();
uint8 t a;
//a = ADCto5bits(b);
//b = measure();
//a = ADCto5bits(b);
//SPI Stuff
//spiSendReceive(a);
while(1) {
  while(digitalRead(GPIOA, 1)!= 1); //wait for button push
  TIMERD->ARR.ARR = (1000 * 2)-1; // Wait for amount of time to pass
  TIMERD -> CCR1.CCR1 = (1000 * 2);
  TIMERD->EGR.UG = 1;
  while(TIMERD->SR.CC1IF == 0) { }
  TIMERD->SR.CC1IF = 0;
  durationTimer(); // Reset Timer
  b = measure(); // Measure with ADC
  a = ADCto5bits(b); //Convert measurement
  //SPI Stuff
  spiSendReceive(a); //Send 5 bit number to FPGA
 while (digitalRead (GPIOA, 4) != 1); // Wait for done signal from FPGA
}
return b+a;
```

```
//11/22/2021
 2
      //George Wang
 3
      //gewang@g.hmc.edu
      //module determining the row we are in
 4
 5
      module Breathylizer
6
7
          (input logic clk.
           input logic load,
8
9
           input logic sck,
           input logic reset,
           input logic sdi, //switches
output logic [6:0] rowTrans, //transistors
output logic [7:0] LEDLogic,
10
11
12
           //output logic [7:0] LEDLogic2,
13
14
           output logic done);
15
           logic [4:0] dataIn;
logic [6:0] row;
logic High;
16
17
18
19
20
           spi SPI(sck, sdi, dataIn);
21
22
23
           clockMulti CMO(clk, High);
24
           LEDFSM FSM0(High, reset, load, row, done);
25
26
27
           numberWrite WriteO(row, dataIn, LEDLogic);
28
          //transistor logic
                                  = ~row[0];
29
           assign rowTrans[0]
           assign rowTrans[1] = ~row[
assign rowTrans[2] = ~row[
30
31
32
           assign rowTrans[3] = ~row[3]
33
           assign rowTrans[4] = ~row[4]
34
           assign rowTrans [5] = \sim row [5]
35
           assign rowTrans[6] = ~row[6];
36
37
      endmodule
38
39
40
     module LEDFSM
41
           (input
                     logic clk,
42
            input
                     logic reset,
            input logic load,
output logic [6:0] row,
output logic done);
43
44
45
46
47
            typedef enum logic [4:0] {R0, R1, R2, R3, R4, R5, R6, R7, R8} statetype;
                                                                                                       //we wont use
      the top LED matrix
48
            statetype state, nextState;
49
50
            //state_register
51
52
            always_ff @(posedge clk, posedge reset)
                if (reset) state <= R0;
53
                else
                                    state <= nextState;</pre>
54
55
            //next state logic
56
            //5 state FSM. 4 record row information
57
            always_comb
                case(state)
58
59
                     R0: if(load) nextState <= R1;</pre>
60
                          else nextState <= R0;</pre>
61
                     R1: if(load) nextState <= R1;</pre>
62
                          else nextState <= R2;</pre>
63
                     R2: if(load) nextState <=
                                                     R1:
64
                          else nextState <= R3;</pre>
65
                     R3: if(load) nextState <=
                                                     R1:
66
                          else nextState <= R4;
67
                     R4: if(load) nextState <= R1;</pre>
68
                          else nextState <= R5;</pre>
69
70
71
72
73
                     R5: if(load) nextState <= R1;</pre>
                          else nextState <= R6;</pre>
                     R6: if(load) nextState <= R1;</pre>
                          else nextState <= R7;</pre>
                     R7: if(load) nextState <= R1;</pre>
74
75
                          <mark>else</mark> nextState <= R8;
                     R8: if(load) nextState <= R1;</pre>
```

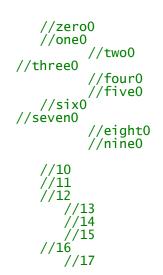
Date: December 06, 2021

Breathylizer.sv

76 77 78	<pre>else nextState <= R2; default: nextState <= R0; endcase</pre>
79 80 81 82 83 84 85 86 87	<pre>assign row[0] = (state == R2); assign row[1] = (state == R3); assign row[2] = (state == R4); assign row[3] = (state == R5); assign row[4] = (state == R6); assign row[5] = (state == R7); assign row[6] = (state == R8);</pre>
88 89 90 91 92	<pre>assign done = ~(state == R0 state == R1); endmodule</pre>
93 94 95 96 97	<pre>module numberWrite (input logic [6:0] row, input logic [4:0] dataIn, //switches output logic [7:0] LEDLogic);</pre>
98 99 100 101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117 118 119	<pre>logic [7:0] zero0, zero1, zero2, zero3, zero4, zero5, zero6; logic [7:0] one0, one1, one2, one3, one4, one5, one6; logic [7:0] two0, two1, two2, two3, two4, two5, two6; logic [7:0] three0, three1, three2, three3, three4, three5, three6; logic [7:0] four0, four1, four2, four3, four4, four5, four6; logic [7:0] five0, five1, five2, five3, five4, five5, five6; logic [7:0] six0, six1, six2, six3, six4, six5, six6; logic [7:0] six0, six1, seven2, seven3, seven4, seven5, seven6; logic [7:0] eight0, eight1, eight2, eight3, eight4, eight5, eight6; logic [7:0] ten0, ten1, ten2, ten3, ten4, ten5, ten6; logic [7:0] onet0, onet1, onet2, onet3, onet4, onet5, onet6; logic [7:0] twot0, twot1, twot2, twot3, twot4, twot5, twot6; logic [7:0] threet0, threet1, threet2, threet3, threet4, threet5, threet6; logic [7:0] fourt0, fourt1, fourt2, fourt3, fourt4, fourt5, fourt6; logic [7:0] fivet0, fivet1, fivet2, fivet3, fivet4, fivet5, fivet6; logic [7:0] sixt0, sixt1, sixt2, sixt3, sixt4, sixt5, sixt6; logic [7:0] eight10, eight11, eight22, eight3, eight44, eight55, eight6; logic [7:0] ninet0, ninet1, ninet2, ninet3, ninet4, ninet5, ninet6;</pre>
120 121 122 123 124 125 126 127 128	<pre>assign zero0 = 8'b00000000; assign zero1 = 8'b01100110; assign zero2 = 8'b01100110; assign zero3 = 8'b01100110; assign zero4 = 8'b01100110; assign zero5 = 8'b01100110; assign zero6 = 8'b00000000;</pre>
129 130 131 132 133 134 135 136	<pre>assign one0 = 8'b00000111; assign one1 = 8'b01100111; assign one2 = 8'b01100111; assign one3 = 8'b01100111; assign one4 = 8'b01100111; assign one5 = 8'b01100111; assign one6 = 8'b00000111;</pre>
137 138 139 140 141 142 143 144	<pre>assign two0 = 8'b0000000; assign two1 = 8'b01101110; assign two2 = 8'b01101110; assign two3 = 8'b01100000; assign two4 = 8'b01100111; assign two5 = 8'b01100111; assign two6 = 8'b00000000;</pre>
145 146 147 148 149 150 151	<pre>assign three0 = 8'b0000000; assign three1 = 8'b0110110; assign three2 = 8'b0110110; assign three3 = 8'b01100000; assign three4 = 8'b0110110; assign three5 = 8'b01101110; assign three6 = 8'b00000000;</pre>

Dute: December	
152 153 154 155 156 157 158 159 160	<pre>assign four0 = 8'b00000110; assign four1 = 8'b01100110; assign four2 = 8'b01100110; assign four3 = 8'b01100100; assign four4 = 8'b01101110; assign four5 = 8'b01101110; assign four6 = 8'b00001110;</pre>
161 162 163 164 165 166 167 168	<pre>assign five0 = 8'b00000000; assign five1 = 8'b01100111; assign five2 = 8'b01100111; assign five3 = 8'b01100100; assign five4 = 8'b01101110; assign five5 = 8'b01101110; assign five6 = 8'b00000000;</pre>
169 170 171 172 173 174 175 176	<pre>assign six0 = 8'b00000000; assign six1 = 8'b01100111; assign six2 = 8'b01100111; assign six3 = 8'b01100000; assign six4 = 8'b01100110; assign six5 = 8'b01100110; assign six6 = 8'b00000000;</pre>
177 178 179 180 181 182 183 184	<pre>assign seven0 = 8'b00000000; assign seven1 = 8'b01101110; assign seven2 = 8'b01101110; assign seven3 = 8'b01101110; assign seven4 = 8'b01101110; assign seven5 = 8'b01101110; assign seven6 = 8'b00001110;</pre>
185 186 187 188 189 190 191 192	<pre>assign eight0 = 8'b00000000; assign eight1 = 8'b01100110; assign eight2 = 8'b01100110; assign eight3 = 8'b01100000; assign eight4 = 8'b01100110; assign eight5 = 8'b01100110; assign eight6 = 8'b00000000;</pre>
193 194 195 196 197 198 199	<pre>assign nine0 = 8'b00000000; assign nine1 = 8'b01100110; assign nine2 = 8'b01100110; assign nine3 = 8'b01100000; assign nine4 = 8'b01101110; assign nine5 = 8'b01101110; assign nine6 = 8'b00001110;</pre>
200 201 202 203 204 205 206 207	<pre>assign ten0 = 8'b01110000; assign ten1 = 8'b01110110; assign ten2 = 8'b01110110; assign ten3 = 8'b01110110; assign ten4 = 8'b01110110; assign ten5 = 8'b01110110; assign ten6 = 8'b01110000;</pre>
208 209 210 211 212 213 214 215	<pre>assign onet0 = 8'b01110111; assign onet1 = 8'b01110111; assign onet2 = 8'b01110111; assign onet3 = 8'b01110111; assign onet4 = 8'b01110111; assign onet5 = 8'b01110111; assign onet6 = 8'b01110111;</pre>
216 217 218 219 220 221 222 222 223	<pre>assign twot0 = 8'b01110000; assign twot1 = 8'b0111110; assign twot2 = 8'b01111110; assign twot3 = 8'b01110000; assign twot4 = 8'b01110111; assign twot5 = 8'b01110111; assign twot6 = 8'b01110000;</pre>
224 225 226 227	<pre>assign threet0 = 8'b01110000; assign threet1 = 8'b0111110; assign threet2 = 8'b01111110;</pre>

assign assign	threet3 = 8'b threet4 = 8'b threet5 = 8'b threet6 = 8'b	01111110 01111110			
assign assign assign assign assign assign	<pre>fourt0 = 8'b0 fourt1 = 8'b0 fourt2 = 8'b0 fourt3 = 8'b0 fourt3 = 8'b0 fourt4 = 8'b0 fourt5 = 8'b0 fourt6 = 8'b0</pre>	1110110 1110110 1110000 1111110 1111110			
assign assign assign assign assign assign	fivet0 = 8'b0 fivet1 = 8'b0 fivet2 = 8'b0 fivet3 = 8'b0 fivet4 = 8'b0 fivet5 = 8'b0 fivet6 = 8'b0	1110111; 1110111; 1110000; 1111110; 1111110;			
assign assign assign assign assign assign	<pre>sixt0 = 8'b01 sixt1 = 8'b01 sixt2 = 8'b01 sixt3 = 8'b01 sixt4 = 8'b01 sixt5 = 8'b01 sixt6 = 8'b01</pre>	110111 110111 110000 110110 110110			
assign assign assign assign assign assign	<pre>sevent0 = 8'b sevent1 = 8'b sevent2 = 8'b sevent3 = 8'b sevent4 = 8'b sevent5 = 8'b sevent6 = 8'b</pre>	01111110; 01111110; 01111110; 01111110; 01111110; 01111110;			
assign assign assign assign assign assign	eightt0 = 8'b eightt1 = 8'b eightt2 = 8'b eightt3 = 8'b eightt4 = 8'b eightt5 = 8'b eightt6 = 8'b	01110110; 01110110; 01110000; 01110110; 01110110;			
assign assign assign assign assign assign	ninet0 = 8'b0 ninet1 = 8'b0 ninet2 = 8'b0 ninet3 = 8'b0 ninet4 = 8'b0 ninet5 = 8'b0 ninet6 = 8'b0	1110110 1110110 1110000 1111110 1111110			
always_co case(r 7'b	ow) 0000001: if else else else else else else else els	if (dataIn if (dataIn if (dataIn if (dataIn if (dataIn if (dataIn if (dataIn if (dataIn	== 5'b00000) == 5'b00001) == 5'b00010) == 5'b00100) == 5'b00101) == 5'b00110) == 5'b00111) == 5'b01000) == 5'b01001)	LEDLOGIC = LEDLOGIC = LEDLOGIC = LEDLOGIC = LEDLOGIC = LEDLOGIC = LEDLOGIC =	one0; two0; three0; four0; five0; six0; seven0; eight0;
	else else else else else else	if (dataIn if (dataIn if (dataIn if (dataIn if (dataIn if (dataIn	== 5'b01010) == 5'b01011) == 5'b01100) == 5'b01101) == 5'b01110) == 5'b10000) == 5'b10001)	LEDLOGIC = LEDLOGIC = LEDLOGIC = LEDLOGIC = LEDLOGIC = LEDLOGIC =	<pre>onet0; twot0; threet0; fourt0; fivet0; sixt0;</pre>



eathyli

Date: Dece	ember 06, 2	021	Breathyli	izer.sv	Project: Breathylizer
304 305	//19		else if (dataIn == 5'b1 else if (dataIn == 5'b1	.0010) LEDLogic = eightt(.0011) LEDLogic = ninet()	; //18
306 307	//15		else LEDLogic = 8'b1111		
308 309 310 311 312 313 314 315 316 317 318		7'b0000010:	if (dataIn == 5'b0 else if (dataIn == 5'b0	00000) LEDLogic = zero1; 0001) LEDLogic = one1; 0010) LEDLogic = two1; 0011) LEDLogic = three1; 0010) LEDLogic = four1; 0010) LEDLogic = five1; 00110) LEDLogic = six1; 00111) LEDLogic = seven1; 0000) LEDLogic = eight1; 01001) LEDLogic = nine1;	<pre>//zero0 //one0 //two0 //three0 //four0 //five0 //six0 //seven0 //eight0 //nine0</pre>
319 320 321 322 323 324 325 326 327 328 329 330 331			else if (dataIn == 5'b0 else if (dataIn == 5'b1 else if (dataIn == 5'b1	<pre>1010) LEDLogic = ten1; 1011) LEDLogic = onet1; 1100) LEDLogic = twot1; 1101) LEDLogic = threet1; 1110) LEDLogic = fourt1; 1111) LEDLogic = fivet1; 0000) LEDLogic = sixt1; 0001) LEDLogic = sevent1; 0010) LEDLogic = eight1; 0011) LEDLogic = ninet1; 1111;</pre>	//10 //11 //12 ; //13 //14 //15 //16 ; //17 ; //18 //19
331 332 333 334 335 336 337 338 339 340 341 342				00000) LEDLogic = zero2; 0001) LEDLogic = one2; 0010) LEDLogic = two2; 0011) LEDLogic = three2; 0010) LEDLogic = four2; 0010) LEDLogic = five2; 00110) LEDLogic = six2; 00111) LEDLogic = seven2; 00100) LEDLogic = eight2; 01001) LEDLogic = nine2;	
343 344 345 346 347 348 349 350 351 352	//19		else if (dataIn == 5'b0 else if (dataIn == 5'b0 else if (dataIn == 5'b1 else if (dataIn == 5'b1 else if (dataIn == 5'b1 else if (dataIn == 5'b1	<pre>1010) LEDLogic = ten2; 1011) LEDLogic = onet2; 1100) LEDLogic = twot2; 1101) LEDLogic = threet2; 1110) LEDLogic = fourt2; 1111) LEDLogic = fivet2; 0000) LEDLogic = sixt2; 0001) LEDLogic = sevent2; 0010) LEDLogic = eightt2; 0011) LEDLogic = ninet2;</pre>	//10 //11 //12 ; //13 //14 //15 //16 ; //17 ; //18
353 354 355			else LEDLogic = 8'b1111		
356 357 358 359 360 361 362 363 364 365 366		7'b0001000:	else if (dataIn == 5'b0 else if (dataIn == 5'b0 else if (dataIn == 5'b0	00000) LEDLogic = zero3; 00001) LEDLogic = one3; 00010) LEDLogic = two3; 00011) LEDLogic = three3; 00100) LEDLogic = four3; 00101) LEDLogic = five3; 00110) LEDLogic = six3; 00111) LEDLogic = seven3; 01000) LEDLogic = eight3; 01001) LEDLogic = nine3;	//six0 //seven0 //eight0
367 368 369 370 371 372 373 374 375 376 377			else if (dataIn == 5'b0 else if (dataIn == 5'b1 else LEDLOgic = 8'b1111	1010) LEDLogic = ten3; 1011) LEDLogic = onet3; 1100) LEDLogic = twot3; 1101) LEDLogic = threet3 1110) LEDLogic = fourt3; 1111) LEDLogic = fivet3; 1000) LEDLogic = sixt3; 1001) LEDLogic = sevent3; 1001) LEDLogic = eightt3; 1001) LEDLogic = ninet3; 1111;	//10 //11 //12 ; //13 //14 //15 //16 ; //17 ; //18 //19

				-		
378 379 380 381 382 383 384 385 386 387 388 388 389		7'b0010000:	if (dataIn else if (dataIn	== 5'b00000) == 5'b00001) == 5'b00010) == 5'b00100) == 5'b00101) == 5'b00101) == 5'b00111) == 5'b01000) == 5'b01001)	LEDLogic = zero4; LEDLogic = one4; LEDLogic = two4; LEDLogic = three4; LEDLogic = four4; LEDLogic = five4; LEDLogic = six4; LEDLogic = seven4; LEDLogic = eight4; LEDLogic = nine4;	<pre>//zero0 //one0 //two0 //three0 //four0 //five0 //six0 //seven0 //eight0 //nine0</pre>
390 391 392 393 394 395 396 397 398 399 400	//19		else if (dataIn else if (dataIn	== 5'b01010) == 5'b01011) == 5'b01100) == 5'b01101) == 5'b01110) == 5'b10000) == 5'b10001) == 5'b10011) == 5'b10011)	LEDLogic = ten4; LEDLogic = onet4; LEDLogic = twot4; LEDLogic = threet4; LEDLogic = fourt4; LEDLogic = fivet4; LEDLogic = sixt4; LEDLogic = sevent4; LEDLogic = eightt4; LEDLogic = ninet4;	//10 //11 //12 //13 //14 //15 //16 //17 //18
401 402	,,,		<pre>else LEDLogic =</pre>	8'b11111111;		
402 403 404 405 406 407 408 409 410 411 412 413 414		7'b0100000:	if (dataIn else if (dataIn	== 5'b00000) == 5'b00001) == 5'b00010) == 5'b00100) == 5'b00100) == 5'b00101) == 5'b00111) == 5'b01000) == 5'b01001)	LEDLogic = zero5; LEDLogic = one5; LEDLogic = two5; LEDLogic = three5; LEDLogic = four5; LEDLogic = five5; LEDLogic = six5; LEDLogic = seven5; LEDLogic = eight5; LEDLogic = nine5;	<pre>//zero0 //one0 //two0 //three0 //four0 //five0 //six0 //seven0 //eight0 //nine0</pre>
415 416 417 418 419 420 421 422 423 424	//19		else if (dataIn else if (dataIn	== 5'b01010) == 5'b01011) == 5'b01100) == 5'b01101) == 5'b01110) == 5'b10000) == 5'b10001) == 5'b10011)	LEDLogic = ten5; LEDLogic = onet5; LEDLogic = twot5; LEDLogic = threet5; LEDLogic = fourt5; LEDLogic = fivet5; LEDLogic = sixt5; LEDLogic = sevent5; LEDLogic = eightt5; LEDLogic = ninet5;	//10 //11 //12 //13 //14 //15 //16 //17
425 426			<pre>else LEDLogic =</pre>	8'b11111111;		
427 428 429 430 431 432 433 434 435 436 437		7'b1000000:	else if (dataIn else if (dataIn	== 5'b00001) == 5'b00010) == 5'b00100) == 5'b00100) == 5'b00100) == 5'b00110) == 5'b00100)	LEDLogic = zero6; LEDLogic = one6; LEDLogic = two6; LEDLogic = three6; LEDLogic = four6; LEDLogic = five6; LEDLogic = six6; LEDLogic = seven6; LEDLogic = eight6; LEDLogic = nine6;	//zero0 //one0 //two0
438 439 440 441 442 443 444 445 446 447 448	//19		else if (dataIn else if (dataIn	== 5'b01011) == 5'b01100) == 5'b01101) == 5'b01110) == 5'b10000) == 5'b10001) == 5'b10010) == 5'b10011)	LEDLogic = ten6; LEDLogic = onet6; LEDLogic = twot6; LEDLogic = threet6; LEDLogic = fourt6; LEDLogic = fivet6; LEDLogic = sixt6; LEDLogic = sevent6; LEDLogic = eightt6; LEDLogic = ninet6;	//14 //15 //16
449 450			else LEDLogic =	0 011111111;		

```
451
452
                     default: LEDLogic = 8'b11111111;
453
454
                endcase
        endmodule
455
456
457
458
        //9/8/21
//George Wang
//Gewang@g.hmc.edu
//module for generating clock signal at around 2.4Hz
//Referenced Better Verilog Counter Idiom
medule clockWulti
459
460
461
462
463
        module clockMulti
464
465
              (input logic clk,
466
               output logic High);
467
468
              logic [15-1:0] LEDHigh;
469
              always_ff @(posedge clk)
470
471
                     LEDHigh <= LEDHigh + 56;
472
473
                               assign High = LEDHigh[14];
474
475
        endmodule
476
477
        module spi(input
                                logic sck,
                       input logic sdi,
output logic [4:0] ADC);
478
479
480
             logic [7:0] ADC8;
always_ff @(posedge sck)
ADC8 = {ADC8[6:0],sdi};
481
482
483
484
485
              assign ADC = ADC8[4:0];
486
487
488
        endmodule
489
```